

Homogenization of Maxwell's equations in bianisotropic materials

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Hellenic–Swedish Workshop, Athens, Greece

Let Ω be a domain in \mathbb{R}^3 and $\partial\Omega$ Lipschitz. We consider the typical Maxwell problem with equations

$$\frac{\partial}{\partial t} D(x, t) = \operatorname{curl} H(x, t) + F(x, t) \quad (1)$$

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$$D(x, t) = \eta E + \xi H + \eta_d \star E + \xi_d \star H \quad (3)$$

$$B(x, t) = \zeta E + \mu H + \zeta_d \star E + \mu_d \star H \quad (4)$$

where η, ξ, ζ and μ are 3×3 matrices. Likely η_d, ξ_d, ζ_d and μ_d are also 3×3 matrices.

Let $u := (E, H)^T$, $J := (F, G)^T$, $d := (D, B)^T$,
 $u^0(x) := (E^0(x), H^0(x))^T$,

$$A(x) := \begin{pmatrix} \eta & \xi \\ \zeta & \mu \end{pmatrix}, G_d(x, t) := \begin{pmatrix} \eta_d & \xi_d \\ \zeta_d & \mu_d \end{pmatrix}$$

and $M := \begin{pmatrix} 0 & \text{curl} \\ -\text{curl} & 0 \end{pmatrix}$

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and $M := \begin{pmatrix} 0 & \text{curl} \\ -\text{curl} & 0 \end{pmatrix}$ then the system becomes (P1)

$$\begin{cases} \frac{\partial}{\partial t}(A(x)u(x, t) + (G_d \star u)(x, t)) = Mu(x, t) + J(x, t) \\ u(x, 0) = u^0(x) \\ \hat{\eta} \times u(x, t) = 0. \end{cases} \quad (5)$$

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We assume that all the fields which are functions of the spatial variable x and the time variable t are considered to be functions of the time variable t in a suitable Banach space.

We also assume that matrix A is symmetric and coercive i.e

$$x^T A(x)x \geq \beta |x|^2, \text{ for any } x \in \mathbb{R}^6.$$

Theorem 1

Let $A \in L^\infty(\Omega; \mathbb{R}^{36})$ and $G_d \in W^{2,1}(0, T; L^\infty(\Omega; \mathbb{R}^{36}))$ be 6×6 matrices, $u^0 \in X_M := H_0(\text{curl}, \Omega) \times H(\text{curl}, \Omega)$ and $J \in W^{1,1}(0, T; L^2(\Omega; \mathbb{R}^6))$ be 6-vectors then the problem (P1) has unique solution

$$u \in W^{1,\infty}(0, T; L^2(\Omega; \mathbb{R}^6)) \cap L^\infty(0, T; X_m)$$

which satisfies the estimate

$$\|u\|_{L^\infty(0, T; X_M)} + \left\| \frac{du}{dt} \right\|_{L^\infty(0, T; L^2(\Omega; \mathbb{R}^6))} \leq c(\|J\|_{W^{1,1}(0, T; L^2(\Omega; \mathbb{R}^6))} + \|u^0\|_{X_M}) \quad (6)$$

where c is a positive constant which depends on $\|A\|_{L^\infty}$ and $\|G_d\|_{L^\infty}$.

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We obtain the existence of the solution using the following lemma:

Lemma 2

If A, R are $m \times m$ matrices with matrix A symmetric and coercive, $K \in W^{r,1}(0, T; \mathbb{R}^{m^2})$ and $B \in W^{r,1}(0, T; \mathbb{R}^m), r = 1, 2$ then the integral equation Voltera

$$AU(t) + \int_0^t (K(t-s) - R)U(s)ds = B(t), \quad t \in [0, T]$$

has a unique solution $U(t) \in W^{r,1}(0, T, \mathbb{R}^m)$.

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In order to proof the lemma we need the Fredholm theory.

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We start with a sequence $e_1, e_2, \dots, e_m, \dots$ of linear independent components of $X_M : \cup \bar{V}_m = X_M$ where $V_m = \langle e_1, e_2, \dots \rangle$, $m \in \mathbb{N}^*$. Looking for a solution of the form

$$u_m(t) = \sum_{k=1}^m h_k^m(t) e_k$$

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$$u_m(t) = \sum_{k=1}^m h_k^m(t) e_k$$

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Step 2: Estimates Firstly, we prove the following equality

$$\int_{\Omega} \frac{d}{dt} (A(x) u_m(t)) u_m(t) dx + \int_{\Omega} \frac{d}{dt} (G_d(t) \star u_m(t)) u_m(t) = \int_{\Omega} J(t) u_m(t) dx \quad (7)$$

which results from the main equation of problem $P1$ and the relations $H \operatorname{curl} E - E \operatorname{curl} H = \operatorname{div}(E \times H)$, $\hat{\eta}(E \times H) = H(\hat{\eta} \times E)$ and the perfect boundary condition $\hat{\eta} \times E$.

Step 3: We prove the equality

$$\begin{aligned}
 (A(x)u_m(t), u_m(t)) &= -2 \int_0^t (\dot{G}(s) \star u_m(s), u_m(s)) ds \\
 &\quad - 2 \int_0^t (G_d(0)u_m(s), u_m(s)) ds \\
 &\quad + (A(x)u_m(0), u_m(0)) + 2 \int_0^t (J(s), u_m(s)) ds. \quad (8)
 \end{aligned}$$

We obtain the above relation by using some other equalities and after some suitable integrations.

Step 4: We estimate each term of the equation (8) and by using the coercivity of A , the Cauchy-Schwartz inequality, the theory of norms and the relation $2ab \leq \epsilon a^2 + \frac{1}{\epsilon} b^2$ for $\epsilon > 0$ we deduce that

$$v_m^2(t) \leq \frac{2}{\beta} \|A\|_{L^\infty} \|u^0\|^2 + \frac{4}{\beta} \|J\|_{L^2} + \frac{2}{\beta} \int_0^t v_m^2(s) \theta(s) ds \quad (9)$$

where β is a constant, $\theta(s) := 2(\int_0^s \|\dot{G}(\sigma)\|_{L^\infty} d\sigma + \|G_d(0)\|_{L^\infty})$ and $v_m(s) := \sup_{0 \leq r \leq s} \|u_m(r)\|_{L^2}$.

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$$\|u_m(t)\|_{L^2} \leq c \sqrt{\|u_0\|_{L^2}^2 + \|J\|_{L^1}^2} \leq c(\|u_0\|_{L^2}^2 + \|J\|_{L^1}^2)$$

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and we obtain the estimate

$$\|u_m\|_{L^\infty(0, T, L^2(\Omega, R^6))} \leq \{\|u_0\|_{X_M} + \|J\|_{L^1(0, T, L^2(\Omega, R^6))}\}.$$

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$$u_m \rightharpoonup u \text{ in } L^\infty(0, T, L^2(\Omega, \mathbb{R}^6))$$

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and as a result $u \in W^{1,\infty}(0, T, L^2(\Omega, \mathbb{R}^6))$. Now, from

$\frac{d}{dt}(Au_m + G_d \star u_m) = Mu_m + j$ we obtain

$\frac{d}{dt} \int_\Omega (Au_m + G_d \star u_m) e_i dx = - \int_\Omega Mu_m e_i dx + \int_\Omega j e_i dx$. Taking into consideration the uniqueness of the weak* limit, the density of V_m in \mathcal{X}_M and the density of \mathcal{X}_M in $L^2(\Omega; \mathbb{R}^6)$ we have

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$$\frac{d}{dt} \int_\Omega (Au + G_d \star u) v dx = \int_\Omega Muv dx + \int_\Omega j v dx \text{ for } v \in X_M.$$

We conclude that u is a weak solution of the initial problem in $L^\infty(0, T, L^2(\Omega; \mathbb{R}^6))$ and supplemented with the above convergences provide the necessary smoothness in u .

The solution u satisfies the conservation law

$$\begin{aligned} \frac{1}{2} \int_{\Omega} (Au, u) dx - \int_0^t \int_{\Omega} j \cdot u dx ds + \int_0^t \int_{\Omega} G(0)u(s) \cdot u(s) dx ds \\ + \int_0^t \int_{\Omega} (\dot{G} \star u(s)) ds \cdot u(s) dx ds = \frac{1}{2} \int_{\Omega} Au^0 \cdot u^0 dx \end{aligned}$$

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Proof.

The proof is based on the definition of the field

$$E(x, t) = \frac{1}{2} d(x, t) \cdot u(x, t),$$

on the property of Maxwell's operator $\int_{\Omega} (Mu) u dx = 0$ and on

$$\frac{d}{dt} (Au, u) = 2(Au, \dot{u}), \quad \frac{d}{dt} (G_d \star u, u) = (\dot{G}_d \star u + G_d(0)u, u) + (G_d \star u, \dot{u})$$

where (\cdot, \cdot) is the L_2 inner product in Ω and \dot{f} is always the derivate referred to time t . □

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As a result, for any $\epsilon > 0$ there is a sequence of electromagnetic fields u^ϵ which are solutions of the evolution problem,

$$\frac{d}{dt}(A^\epsilon u^\epsilon + G_d^\epsilon \star u^\epsilon) = M u^\epsilon - j^\epsilon, (0, T) \times \Omega$$

$$u^\epsilon(0, x) = u^{0,\epsilon}(x), \Omega$$

$$\hat{\eta}(x) \times u_1^\epsilon(t, x) = 0, (0, T) \times \partial\Omega.$$

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Purpose: The study of the asymptotic behavior of solution u^ϵ under the following assumptions:

- $u^{\epsilon,0} \rightarrow u^0$ strongly in X_M
- $J^\epsilon \rightarrow J$ strongly in $W^{1,1}(0, T; L^2(\Omega; \mathbb{R}^6))$
- A^ϵ , G_d^ϵ are periodic matrices

Let $\epsilon > 0$. We assume $Y = (0, 1)^3$

$$\mathbb{Z}_\epsilon^3 := \{m \in \mathbb{Z}^3 : \epsilon(m + Y) \subset \Omega\}$$

$$\Omega_\epsilon := \bigcup_{m \in \mathbb{Z}_\epsilon^3} \epsilon(m + Y)$$

$$\Lambda_\epsilon := \Omega - \Omega_\epsilon$$

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Definition 3

The periodic unfolding operator $\mathcal{T}_\epsilon : L^2(\Omega; \mathbb{R}) \rightarrow L^2(\Omega \times Y; \mathbb{R})$ is defined by

$$(\mathcal{T}_\epsilon v)(x, y) := \begin{cases} v(\epsilon[\frac{x}{\epsilon}] + \epsilon y), & x \in \Omega_\epsilon, y \in Y \\ 0, & x \in \Lambda_\epsilon, y \in Y \end{cases}$$

We can apply the unfolding operator on functions with entries functions or matrices and we have that

$$(\mathcal{T}_\epsilon A^\epsilon)(x, y) = A(y)$$

$$(\mathcal{T}_\epsilon G^\epsilon)(x, y, t) = G(y, t).$$

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From the previous definitions we deduce the following properties:

- $\mathcal{T}_\epsilon(au + bv) = a\mathcal{T}_\epsilon u + b\mathcal{T}_\epsilon v$
- $\mathcal{T}_\epsilon(uv) = (\mathcal{T}_\epsilon u)(\mathcal{T}_\epsilon v)$
- $\int_\Omega u(x)dx = \frac{1}{|Y|} \int_{\Omega \times Y} (\mathcal{T}_\epsilon u)(x, y) dy dx.$

Theorem 4

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- ③ If $u^\epsilon \in H(\text{curl}, \Omega) : \|u^\epsilon\|_{H(\text{curl}, \Omega)} \leq c$ for any $\epsilon > 0$ then there are three fields u, v, w which $u \in H(\text{curl}, \Omega)$, $v \in L^2(\Omega, H_{\text{per}}^1(Y; R))$, $W \in L^2(\Omega, H_{\text{per}}^1(Y; \mathbb{R}^3))$, $\text{div}_y w = 0$ and subsequence $\{u^\epsilon\}$ of $\{u^\epsilon\}$ in order to have the following convergences:

$$u^\epsilon \rightharpoonup u \text{ in } H(\text{curl}, \Omega)$$

$$\mathcal{T}_\epsilon u^\epsilon \rightarrow u + \nabla_y v \text{ in } L^2(\Omega \times Y; \mathbb{R}^3)$$

$$\mathcal{T}_\epsilon(\text{curl } u^\epsilon) \rightarrow \text{curl}_x u + \text{curl}_y w \text{ in } L^2(\Omega \times Y; \mathbb{R}^3).$$

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By using the above theorem and and the conservation law for the solution u^ϵ we have the next theorem:

Theorem 5

If $u^\epsilon(x, t)$, $x \in \Omega$, $t > 0$ the unique solution of (P_H) in $W^{1,\infty}(0, T; L^2(\Omega; \mathbb{R}^6)) \cap L^\infty(0, T; X_M)$ and u, v, w satisfying theorem 4 we obtain

$$\begin{aligned} & \frac{1}{2} \int_{\Omega \times Y} A(u(t) + \nabla_y v(t))(u(t) + \nabla_y v(t)) \\ & + \int_0^t \int_0^{t_1} \int_{\Omega \times Y} \dot{G}(t_1 - s)(u(s) + \nabla_y v(s))(u(t_1) + \nabla_y v(t_1)) \\ & + \int_0^t \int_{\Omega \times Y} G(0)(u(s) + \nabla_y v(s))(u(s) + \nabla_y v(s)) \\ & + \int_0^t \int_{\Omega \times Y} J(s)u(s) = \frac{1}{2} \int_{\Omega \times Y} Au^0 u^0. \end{aligned}$$

Theorem 5

If $u^\epsilon(x, t)$, $x \in \Omega$, $t > 0$ the unique solution of (P_H) in $W^{1,\infty}(0, T; L^2(\Omega; \mathbb{R}^6)) \cap L^\infty(0, T; X_M)$ and u, v, w satisfying theorem 4 we obtain

$$\begin{aligned} & \frac{1}{2} \int_{\Omega \times Y} A(u(t) + \nabla_y v(t))(u(t) + \nabla_y v(t)) \\ & + \int_0^t \int_0^{t_1} \int_{\Omega \times Y} \dot{G}(t_1 - s)(u(s) + \nabla_y v(s))(u(t_1) + \nabla_y v(t_1)) \\ & + \int_0^t \int_{\Omega \times Y} G(0)(u(s) + \nabla_y v(s))(u(s) + \nabla_y v(s)) \\ & + \int_0^t \int_{\Omega \times Y} J(s)u(s) = \frac{1}{2} \int_{\Omega \times Y} Au^0 u^0. \end{aligned}$$

The solution u^ϵ satisfies the uniform bound

$$\|u^\epsilon\|_{L^\infty(0, T; X_M)} + \left\| \frac{du^\epsilon}{dt} \right\|_{L^\infty(0, T; L^2(\Omega; \mathbb{R}^6))} \leq c(\|J^\epsilon\|_{W^{1,1}(0, T; L^2(\Omega, \mathbb{R}^6))} + \|u^{\epsilon, 0}\|_{X_M})$$

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Theorem 6

Let $A^\epsilon \in L^\infty(\Omega; \mathbb{R}^{36})$ and $G_d^\epsilon \in W^{2,1}(0, T; L^\infty(\Omega; \mathbb{R}^{36}))$ be two matrices satisfying assumption 3 stated before. Also, the initial condition $u^{\epsilon,0}$ and the source J^ϵ satisfy assumptions 1,2 respectively then if we assume u^ϵ to be the solution of (P_H) there exists three fields u, v, w with

$$u \in W^{1,\infty}(0, T; L^2(\Omega; \mathbb{R}^6)) \cap L^\infty(0, T, X_M)$$

$$v \in W^{1,\infty}(0, T; L^2(\Omega; H_{per}^1(Y; \mathbb{R}^2)))$$

$$w \in L^\infty(0, T; L^2(\Omega; H_{per}^1(Y; \mathbb{R}^6)))$$

Now we are in position to state and prove the next important result:

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$$w \in L^\infty(0, T; L^2(\Omega; H_{per}^1(Y; \mathbb{R}^6)))$$

i) which are limits as follows

$$u^\epsilon \rightharpoonup u \text{ weakly}^* \text{ in } L^\infty(0, T; X_M)$$

$$\mathcal{T}_\epsilon u^\epsilon \rightarrow u + \nabla_y v \text{ strongly in } H^1(0, T; L^2(\Omega \times Y; \mathbb{R}^6))$$

$$\mathcal{T}_\epsilon(\text{curl } u^\epsilon) \rightarrow \text{curl}_x u + \text{curl}_y w \text{ strongly in } L^2((0, T) \times \Omega \times Y; \mathbb{R}^6)$$

ii) which solve the evolution problem:

$$\begin{aligned} \frac{d}{dt}(A(y)(u(x, t) + \nabla_y v(x, y, t))) + (G_d \star (u + \nabla_y v)(t)) \\ = M_x u(x, t) + M_y w(x, y, t) + J(x, t) \\ u(0) + \nabla_y v(x, y, 0) = u^0 \\ \hat{\eta} \times u_1 = 0 \end{aligned}$$

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Proof.

- Step 1: weak convergence
- Step 2: boundary condition
- Step 3: strong convergence



Thank you!